Global Water

MODBUS MANUAL
For the
CL500
Online Residual
Chlorine Monitor

Global Water 11390 Amalgam Way Gold River CA 95670 Phone: 800-876-1172

Fax: 847-672-9988

EMail:<u>Globalw@globalw.com</u>
Website: <u>www.globalw.com</u>

Revised (3/09) Rev. 1.3

1.0 Overview

The Global Water CL500 uses a communication protocol called Modbus. A company called Modicon, for use with their programmable controllers, developed the Modbus protocol. Since that time Modbus has evolved into common communication protocol in industry.

The communication method involves using a master-slave technique, in which there is one master and several slaves. The CL500 is a slave device. Only the master can initiate queries. These queries are directed to an individual slave device and the appropriate slave responds with the requested data.

A broadcast message can be sent to all slaves. The slave devices do not answer these broadcasts.

There are two transmission modes. These modes are known as RTU (Remote Terminal Unit) and ASCII (American Standard Code for Information Interchange).

The CL500 can be setup in a network of up to 255 slave devices. Each device must have a different address (1-255). The CL500 can be set for either RTU or ASCII mode.

2.0 Electrical Connections

All of the electrical connections to the instrument are made at the termination area, which is located on the portion of the instrument. The connections are labeled and are self-descriptive (see Figure 1). Please follow all local and government recommendations and methods for installation of electrical connections to and between the instrument and other peripheral devices.

Plugs are inserted into cable bulkheads when shipped, to ensure a watertight seal. These plugs should be removed and discarded as required when cabling to this connection.

The bulkhead will accept cable diameters from 5.8mm (.230 in.) up to 10 mm (.395 in.). The terminals are designed to accept wires in the range of 14-28 AWG. All wires should be stripped to a length of 6 mm

It is the user's responsibility to assure that the watertight seal is maintained after the terminal box has been wired for operation. If any of the bulkheads are not tightened properly around a cable or plug, the ratings of the instrument will be jeopardized and there is a possibility of creating a shock hazard.

Note: Only qualified electricians should be allowed to perform the installation of the instrument as it involves a line voltage that could endanger life.

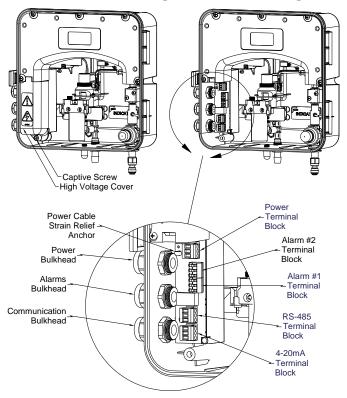


Figure 1: Electrical Connections for the Instrument

2.1 RS-485 Connection

The RS-485 half-duplex (2-wire) digital interface operates with differential levels that are not susceptible to electrical interferences. This is why cable lengths up to 3000 ft can be implemented. The last device on every bus may require a 120-ohm termination resistor to eliminate the possibilities of signal reflection on the line. Do not run RS-485 cables in the same conduit as power.

Ensure each instrument is not powered when connecting the RS-485 line. To prevent damage to the instrument, ensure that power is disconnected prior to making connections.

3.0 Operation

3.1 Configuring the RS-485 Port

The CL500 is equipped with an RS-485 port which operates in one of three ways (see the operator's manual for more information).

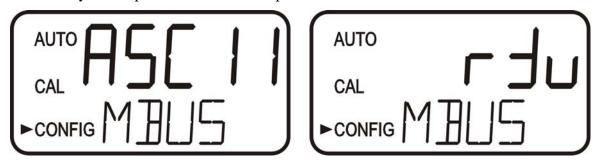
Select the correct baud rate (1200, 2400, 4800, 9600, or 19200) for operation of the I/O port by pressing the ♠ or ▼ buttons to change the displayed baud rate.



Press the \d button to continue on and select the desired instrument address (1-255) using the \d or \d buttons. Once the selection is satisfactory, press the \d button.



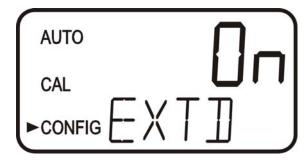
Select the operating mode either ASCII or RTU using the ♠ or ▼ buttons. Press the **MODE** key to complete the Modbus setup.



3.1 Configuring the RS-485 Port (continued)

For Modbus some applications, especially involving the ASCII operation mode, it may be necessary to set a different protocol than the default setting (8 bits, 1 stop bit, no parity). Menus are available for this in the Extended Settings portion of the configuration **CONFIG** mode.

While in the **CONFIG** mode, press the $\[\]$ button, several times until the Extended Settings is as shown below. Select **On** using the $\[\]$ or $\[\]$ buttons.

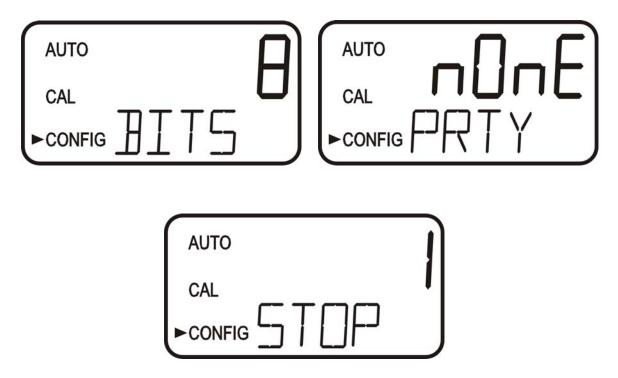


Press the

button a few times until the menus appear for **BITS**, **PRTY** (Parity) and **STOP** (Stop Bits). Set each one to the desired setting using the

and

buttons.



4.0 The Modbus RS-485 Output & Commands Implemented

The default communication parameters are 8 bits, no parity and 1 stop bit. Please note that all Modbus communication is via RS-485. The instruments can support a two wire multidrop network of 255 units. If the connection is to the master on USB, an RS-485 to USB converter is required.

4.1 Coils

These single-bit values are readable and changeable from the master. The data will be returned with the lowest addressed coil in the LSB of the data. Unused bits in the data will be set to 0. True is a 1 and False is 0.

4.1.1 Valid Command(s)

| Code | Name | Broadcast |
|------|-------------------|-----------|
| 0x01 | Read Coil Status | No |
| 0X05 | Force Single Coil | Yes |

4.1.2 Format

16-bit word format

| MSB | | | | | | | | | | | | | | | LSB |
|--------|--------|--------|--------|--------|--------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |

4.1.3 Valid Addresses

00001 - 00XXX

4.1.4 Definitions

| Address | Function | Default |
|---------|---------------------|---------|
| 00001 | Access code enabled | False |
| 00002 | RS-485 enabled | True |
| 00003 | 4-20 mA enabled | False |

4.2 Input Status

These single-bit values are readable from the master. The data will be returned with the lowest addressed input status in the LSB of the data. Unused bits in the data will be set to 0.

4.2.1 Valid Command(s)

| Code | Name | Broadcast |
|------|-------------------|-----------|
| 0x02 | Read Input Status | No |

4.2.2 Format

16-bit word format

| MSB | | | | | | | | | | | | | | | LSB |
|--------|--------|--------|--------|--------|--------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |

4.2.3. Valid Addresses

10001 - 10XXX

4.2.4 Definitions

| Address | Function | Default |
|---------|---|---------|
| 10001 | Instrument error | False |
| 10002 | Instrument error with alarm (levels 1,2and 3) | False |
| 10003 | Alarm 1 active | False |
| 10004 | Alarm 2 active | False |

4.3 Holding Registers

These 16-bit values are readable and changeable from the master. The data is stored and transmitted with the MSB first and then the LSB.

4.3.1 Valid Command(s)

| Code | Name | Broadcast |
|------|---------------------------|-----------|
| 0x03 | Read Holding Registers | No |
| 0x06 | Preset Single Register | Yes |
| 0X16 | Preset Multiple Registers | Yes |

4.3.2 Format

Float – stored in two consecutive addresses, with the first address containing the least significant word (lower part of mantissa) and the second address containing the most significant word (sign, exponent, and upper part of mantissa).

4.3.3 Valid Addresses

40001 - 40XXX

4.3.4 Definitions

| Address | Type | Register | Min | Default | Max | Function |
|--------------|-------|------------------|-----|---------|------|--------------------|
| 40001 | Int | Decimal places | 0 | 2 | 3 | 0 - XXXXX |
| | | | | | | 1 - XXXX.X |
| | | | | | | 2 - XXX.XX |
| | | | | | | 3 – XX.XXX |
| 40002 | Int | Units (scaling) | 0 | 0 | 1 | 0 - PPM |
| | | | | | | 1 - MG/L |
| 40003 | Int | # of Readings | 1 | 2 | 5 | Number of Readings |
| | | | | | | Used in Averaging |
| 40004 | Int | LCD backlight | 1 | 8 | 10 | Higher is brighter |
| 40005, 40006 | Float | 4-20 mA | 0.0 | 0.00 | 10.0 | Scaling value |
| | | minimum value | | | | |
| 40007, 40008 | Float | 4-20 mA | 0.0 | 6.00 | 10.0 | Scaling value |
| | | maximum value | | | | _ |
| 40009 | Int | 4-20 mA error | 0 | 2 | 3 | 0 - Off |
| | | alarm output | | | | 1-0 mA |
| | | _ | | | | 2-2 mA |
| | | | | | | 3-4 mA |
| 40010 | Int | RS-485 baud | 0 | 3 | 4 | 0 - 1,200 |
| | | | | | | 1 - 2,400 |
| | | | | | | 2 - 4,800 |
| | | | | | | 3 – 9,600 |
| | | | | | | 4 - 19,200 |
| 40011 | Int | RS-485 data bits | 0 | 1 | 1 | 0-7 bits |
| | | | | | | 1-8 bits |
| 40012 | Int | RS-485 parity | 0 | 0 | 2 | 0 – None |
| | | | | | | 1 – Even |

| Address | Type | Register | Min | Default | Max | Function |
|--------------|-------|-------------------|-----|---------|------|--------------------|
| | | | | | | 2 Odd |
| 40013 | Int | RS-485 stop bits | 0 | 0 | 1 | 0 – One |
| | | | | | | 1 Two |
| 40014 | Int | Instrument | 1 | 1 | 255 | |
| | | address | | | | |
| 40015 | Int | Modbus serial | 0 | 0 | 1 | 0 – RTU |
| | | mode | | | | 1 – ASCII |
| 40016 | Int | Alarm 1 type | 0 | 0 | 2 | 0 - Off |
| | | | | | | 1 – Low alarm |
| | | | | | | 2 – High alarm |
| | | | | | | 3 – Error alarm |
| 40017, 40018 | Float | Alarm 1 set point | 0.0 | 1.0 | 10.0 | |
| 40019 | Int | Alarm 2 type | 0 | 0 | 2 | 0 - Off |
| | | | | | | 1 – Low alarm |
| | | | | | | 2 – High alarm |
| | | | | | | 3 – Error alarm |
| 40020, 40021 | Float | Alarm 2 set point | 0.0 | 1.0 | 10.0 | |
| 40022, 40023 | | | | | | Unused |
| 40024 | Int | Measurement | 90 | 150 | 600 | Seconds between |
| | | period | | | | measurements |
| 40025 | Int | Water | 0 | 0 | 1 | Water Conservation |
| | | Conservation | | | | Flag |
| 40026 | | | | | | Unused |

4.4 Input Registers

These 16-bit values are readable by the master. The data is stored with the MSB first and then the LSB.

4.4.1 Valid Command(s)

| Code | Name | Broadcast |
|------|----------------------|-----------|
| 0x04 | Read Input Registers | No |

4.4.2 Format

Float – stored in two consecutive addresses, with the first address containing the least significant word (lower part of mantissa) and the second address containing the most significant word (sign, exponent, and upper part of mantissa).

4.4.3 Valid Addresses

30001 - 30XXX

4.4.4 Definitions

| Address | Type | Register | Value | Function |
|--------------|-------|-----------------------|---------|--|
| 30001, 30002 | Float | Sensor reading | | The meter reading |
| 30003, 30004 | Float | Sensor reading raw | | Sensor reading to six significant places |
| 30005 | Int | Version major | | Software version major number |
| 30006 | Int | Version minor | | Software version minor number |
| 30007 | Int | Version revision | | Software version revision number |
| 30008 | Int | Model number | | Product number |
| 30009 | Int | Model suffix number | | Options – model dependent |
| 30010 | Int | Reading status | 0 | unknown |
| | | | 1 | normal |
| | | | 2 | Over range |
| | | | 3 | Under range |
| | | | 4 | need standard |
| | | | 5 | need sample |
| | | | 6 | reading problem (<i>Err</i>) |
| 30011 | Int | PCB Revision | 0 | Revision 1 |
| | | | 1 | Revision 2 |
| 30012 | Int | Instrument error | 0x0000 | normal |
| | | summary (bit-mapped) | 0x0001 | Error |
| | | | 0x0002 | Alarm 1 is active |
| | | | 0x0004 | Alarm 2 is active |
| | | | 0x0008 | Calibration error |
| 30013, 30014 | Long | Level 4 Errors (bit- | 0x00000 | Normal |
| | | mapped), least severe | 0x00001 | Alarm 1 active (ALM1) |
| | | | 0x00002 | Alarm 2 active (ALM2) |
| | | | 0x00004 | Data over-range (OVER) |
| | | | 0x00008 | Reading error (<i>Err</i>) |

| A | 30015, 30016 | Long | Level 3 Errors (| bit- | 0x00000 | Normal |
|--|--------------|------|----------------------|------|---------|---|
| Society Soci | 50015, 50010 | Long | ` | OIL- | | |
| Note | | | , | | | |
| Note | | | | • | | ` ' |
| No.00010 Intake water fill slow (SLOW) | | | | • | | , , |
| Note | | | | | | , , |
| Substituting | | | | | 0x00010 | Intake water fill slow (SLOW) |
| South | | | | | 0x00020 | Purge is slow (<i>PURG</i>) |
| Substitution Subs | | | | | 0x00040 | Purge clogged (NPRG) |
| Note | | | | | 0x00080 | Cannot determine intake water level (<i>H2O</i>) |
| | | | | | 0x00100 | Intake solenoid stuck open (ISOL) |
| November November | | | | , | 0x00200 | Purge solenoid stuck closed (PSOL) |
| November November November November November | | | | | 0x00400 | Problem with reagent (RGNT) |
| 1000 | | | | | 0x00800 | Sample chamber glass too dark (GLAS) |
| 10017, 30018 | | | | | 0x01000 | Water calibration invalid (WCAL) |
| Long | | | | | 0x02000 | Reagent is old and needs to be replaced (<i>REPL</i>) |
| $30019, 30020 \text{Long} \\ \text{In apped}) \text{mapped}) \begin{array}{l} 0x00001 \text{POST error} \ (POST) \\ 0x00002 \text{Visible lamp blown} \ (GRN0) \\ 0x00008 \text{Visible lamp stuck on} \ (GRN1) \\ 0x00008 \text{Visible lamp optimization problem} \ (GRN2) \\ 0x00010 \text{IR lamp blown} \ (WTR0) \\ 0x00020 \text{IR lamp stuck on} \ (WTR1) \\ 0x00040 \text{IR lamp optimization problem} \ (WTR2) \\ 0x00080 \text{Solenoid power supply} \ (SOL0) \\ 0x00100 \text{Intake solenoid} \ (SOL1) \\ 0x00200 \text{Purge solenoid} \ (SOL2) \\ 0x00400 \text{Reagent solenoid} \ (SOL3) \\ 0x000001 \text{MSP oscillator} \\ 0x000002 \text{MSP A/D} \\ 0x000002 \text{MSP flash data read} \\ 0x000004 \text{MSP flash data write} \\ 0x00010 \text{A/D problem} \\ 0x000020 \text{S/W MicOS queue overflow} \\ 0x000040 \text{S/W stack overflow} \\ 0x000040 \text{S/W stack overflow} \\ 0x000080 \text{S/W invalid PWM port} \\ 0x000100 \text{S/W options missing} \\ \end{array}$ | | | | | 0x04000 | Adjust calibration error (ACAL) |
| November November | 30017, 30018 | Long | · · | bit- | 0x00000 | Normal |
| 0x00004 Visible lamp stuck on (GRN1) | | | mapped) | | 0x00001 | POST error (<i>POST</i>) |
| 30019, 30020 Long Level 1 Errors (bit-mapped), most severe Errors (bit-mapped), most severe 1 Errors (bit-mapped), most severe 0x00010 MSP oscillator 0x000020 MSP A/D 0x00004 MSP flash data read 0x00004 MSP flash data write 0x00010 A/D problem 0x00004 S/W stack overflow 0x00006 S/W invalid PWM port 0x00100 S/W options missing 0x00010 | | | | | 0x00002 | Visible lamp blown (GRN0) |
| 0x00010 IR lamp blown (WTR0) | | | | | 0x00004 | Visible lamp stuck on (GRN1) |
| | | | | | 0x00008 | Visible lamp optimization problem (GRN2) |
| 0x00040 IR lamp optimization problem (WTR2) | | | | | 0x00010 | IR lamp blown (WTRO) |
| 0x00080 Solenoid power supply (SOLO) | | | | | 0x00020 | IR lamp stuck on (WTR1) |
| $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$ | | | | | 0x00040 | IR lamp optimization problem (WTR2) |
| 0x00200 Purge solenoid (SOL2) | | | | | 0x00080 | Solenoid power supply (SOL0) |
| 30019, 30020 Long Level 1 Errors (bit-mapped), most severe | | | | | 0x00100 | Intake solenoid (SOL1) |
| Long Level 1 Errors (bit-mapped), most severe 0x00000 Normal 0x00001 MSP oscillator 0x00002 MSP A/D 0x00004 MSP flash data read 0x00008 MSP flash data write 0x00010 A/D problem 0x00020 S/W MiCOS queue overflow 0x00040 S/W stack overflow 0x00040 S/W invalid PWM port 0x00100 S/W options missing S/W options S/W options missing S/W options S/W options | | | | | 0x00200 | Purge solenoid (SOL2) |
| mapped), most severe 0x00001 MSP oscillator | | | | | 0x00400 | Reagent solenoid (SOL3) |
| 0x00002 MSP A/D 0x00004 MSP flash data read 0x00008 MSP flash data write 0x00010 A/D problem 0x00020 S/W MiCOS queue overflow 0x00040 S/W stack overflow 0x00080 S/W invalid PWM port 0x00100 S/W options missing | 30019, 30020 | Long | Level 1 Errors (bit- | | 0x00000 | Normal |
| 0x00004MSP flash data read0x00008MSP flash data write0x00010A/D problem0x00020S/W MiCOS queue overflow0x00040S/W stack overflow0x00080S/W invalid PWM port0x00100S/W options missing | | | mapped), most seve | ere | 0x00001 | MSP oscillator |
| 0x00008MSP flash data write0x00010A/D problem0x00020S/W MiCOS queue overflow0x00040S/W stack overflow0x00080S/W invalid PWM port0x00100S/W options missing | | | | | | |
| 0x00010A/D problem0x00020S/W MiCOS queue overflow0x00040S/W stack overflow0x00080S/W invalid PWM port0x00100S/W options missing | | | | | | |
| 0x00020 S/W MiCOS queue overflow 0x00040 S/W stack overflow 0x00080 S/W invalid PWM port 0x00100 S/W options missing | | | | ļ | | |
| 0x00040S/W stack overflow0x00080S/W invalid PWM port0x00100S/W options missing | | | | ŀ | | * |
| 0x00080S/W invalid PWM port0x00100S/W options missing | | | | | | |
| 0x00100 S/W options missing | | | | | | |
| | | | | | | • |
| | | | | | 0x00100 | S/W sensor type option |

Note: Error messages shown in Prentiss and in (Italics)

4.5 Exception Responses Implemented

| Code | Name | Meaning |
|------|----------------------|--|
| 00 | | No error |
| 01 | ILLEGAL FUNCTION | The function code is not allowed in the device. |
| 02 | ILLEGAL DATA ADDRESS | The data address is not allowed in the device |
| 03 | ILLEGAL DATA VALUE | A value contained in the query field is wrong for the device |